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Chig -

Programmable Array Logic (PAL®) **High Speed PAL Series 20 AP**

General Description

The PAL family utilizes National Semiconductor's Schottky TTL process and bipolar PROM fusible-link technology to provide user-programmable logic to replace conventional SSI/MSI gates and flip-flops. Typical chip count reduction gained by using PALs is greater than 4:1.

The family lets the systems engineer customize his chip by opening fusible links to configure AND and OR gates to perform his desired logic functions. Complex interconnections that previously required time-consuming layout are thus transferred from PC board to silicon where thay can be easily modified during prototype checkout or production.

The PAL transfer function is the familiar sum of products with a single array of fusible links. Unlike the PROM, the PAL is a programmable AND array driving a fixed OR array. (The PROM is a fixed AND array driving a programmable OR array). In addition, the PAL family offers these options:

- Variable input/output in ratio
- Programmable TRI-STATE® outputs
- Registers and feedback

Unused inputs are tied directly to V_{CC} or GND. Product terms with all fuses blown assume the logical high state, and product terms connected to both true and complement of any single input assume the logical low state. Registers consist of D-type flip-flops that are loaded on the low-tohigh transition of the clock. The registers power up with high (VOH) at the output pin, regardless of the polarity fuse. PAL logic diagrams are shown with all fuses blown, enabling the designer use of the diagrams as coding sheets.

The entire PAL family is programmed on inexpensive conventional PROM programmers with appropriate personality and socket adapter cards. Once the PAL is programmed and verified, two additional fuses may be blown to defeat

verification. This feature gives the user a proprietary circuit which is very difficult to copy.

Functional Description

The PAL Series 20AP represents an enhancement of existing PAL architectures which provides greater design flexibility and improved testability. Several new features have been incorporated into the family, including programmable output polarity, power-up reset, and register preload.

The programmable output polarity feature allows the user to program individual outputs either active high or active low. This feature eliminates any possible need for inversion of signals outside the device.

The registered members of the Series 20AP have been designed to reset during system power-up. Upon application of power, all registers are initialized to a logic 0 state, setting all outputs to a logic 1.

The testability of the registered devices has been increased through the use of the preload feature. During testing, registers can be loaded with any arbitrary state value, thereby allowing full logical verification.

Features

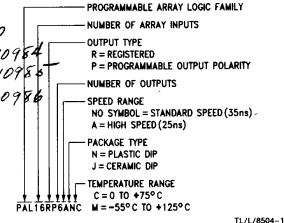
- Programmable output polarity
- Power up reset for all registers
- Preload feature during testing
- Programmable replacement for TTL logic
- Simplifies prototyping and board layout
- Skinny DIP packages
- Reliable tungsten fuses
- 25 ns max. propagation delay

Ordering Information

Part Number	Description	PROGRAMMABLE ARE
PAL16P8A	OCTAL 16 Input AND-OR Gate Array 0166	NUMBER OF ARRAY OUTPUT TYPE
PAL16RP8A	OCTAL 16 Input Registered AND-OR Gate Array	010984 R = REGISTERED
PAL16RP6A		NUMBER OF OUTPUT
PAL16RP4A		010986 SPEED RANGE
PAL Part Nu	nbers	NO SYMBOL = STAN A = HIGH SPEED (25

The PAL part number reveals the logic operation the part performs. The example shown, the PAL16RP6ANC, is a device that accommodates 16 input terms and generates 6 register output terms. It is contained in a 20-pin plastic dualin-line package and meets commercial temperature range specifications.

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RRD-B20M16/Printed in U. S. A.

Absolute Maximum Ratings

Operating Programming

Supply Voltage, V_{CC}

7V

12V

Input Voltage Off-State Output Voltage 5.5V 5.5V 12V*** 12V

Storage Temperature

-65°C to +150°C

Specifications for Military/Aerospace products are not contained in this datasheet. Refer to the associated reliability electrical test specifications document.

Recommended Operating Conditions

	Parameter Supply Voltage			Military			Commercial			11-14-
Symbol				Min	Тур	Max	Min	Тур	Max	Units
V _{CC}				4.5	5	5.5	4.75	5	5.25	٧
	t _w Width of Clock		Low	25	14		20	14		ns
t _w			High	15	6		10	6		1.0
	Setup Time from Input	16RP8A	Polarity Fuse Intact	30	15		25	15		ns
t _{su}	or Feedback to Clock	16RP6A 16RP4A	Polarity Fuse Blown	35	20		30	20		ns
th	Hold Time			0	-10		0	-10		ns
TA	Operating Free-Air Temperature			-55			0		75	°C
T _C	Operating Case Temperature					125				°C

Electrical Characteristics Over Recommended Operating Temperature Range

Symbol	Parameter		Test Conditions		Min	Тур	Max	Units
V _{IH} *	High Level Input Voltage				2			٧
V _{IL} *	Low Level Input Voltage						0.8	v
V _{IC}	Input Clamp Voltage	V _{CC} = Min., I _t	= -18 mA			-0.8	-1.5	٧
	11'-b 1 1 O A A V-16	V _{CC} = Min.			2.4			>
V _{OH}	High Level Output Voltage	$V_{IL} = 0.8V$ $V_{IH} = 2V$	$I_{OH} = -3.2 \text{ mA}$	СОМ	2.4	2.8		
	1 1 O - 1 1 V - 11	V _{CC} = Min.	I _{OL} = 12 mA	MIL		0.3	0.5	v
V _{OL}	Low Level Output Voltage	$V_{IL} = 0.8V$ $V_{IH} = 2V$	I _{OL} = 24 mA	СОМ		0.3	0.5	<u> </u>
lozh	0,000	V _{CC} = Max.	V _O = 2.4V				100	μΑ
lozL	Off-State Output Current †	$V_{IL} = 0.8V$ $V_{IH} = 2V$	V _O = 0.4V				- 100	μΑ
-l _l	Maximum Input Current	V _{CC} = Max.,	V _I = 5.5V				1	mA
- Ін	High Level Input Current†	$V_{CC} = Max., V_I = 2.4V$					25	μΑ
- I _{IL}	Low Level Input Current †	V _{CC} = Max., V _I = 0.4V				-0.04	-0.25	mA
los_	Output Short-Circuit Current**	$V_{CC} = 5V, V_O = 0V$			-30	-70	-130	mA
T _{CC}	Supply Current	V _{CC} = Max.				140	180	mA

[†] I/O pin leakage is the worst case of IOZX or IIX e.g. IIL and IOZH.

These are absolute voltages with respect to pin 10 on the device and include all overshoots due to system and/or tester noise. Do not attempt to test these
values without suitable equipment.

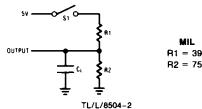
^{**} Only one output shorted at a time.

^{***} Pins 1 and 11 may be raised to 20V max.

Switching Characteristics Over Recommended Ranges of Temperature and V_{CC} Military: $T_A = -55^{\circ}C$ to $+125^{\circ}C^{\circ}$, $V_{CC} = 5V \pm 10\%$. Commercial: $T_A = 0^{\circ}C$ to $75^{\circ}C$, $V_{CC} = 5V \pm 5\%$

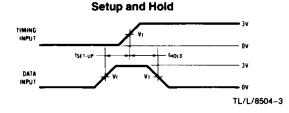
	Parameter		Test	Military			Commercial			11-14-
Symbol	Par L	Conditions	Min	Тур	Max	Min	Тур	Max	Units	
	16P8A, 16RP6A, 16RP4A	Polarity Fuse Intact			15	30		15	25	
IPD /	Input or Feedback to Output	Polarity Fuse Blown			20	33		20	(30)	ns
t _{CLK}	Clock to Output or Feedback			10	20		10	15	ns	
t _{PZX}	Pin 11 to Output Enable Exce	$R_1 = 200\Omega$		10	25		10	20	ns	
t _{PXZ}	Pin 11 to Output Disable Exce	Pin 11 to Output Disable Except 16P8A			11	25		11	20	ns
t _{PZX}	Input to Output Enable	16RP4A, 16RP6A, and 16RP8A			10	30		10	25	ns
t _{PXŽ}	Input to Output Disable	16RP4A, 16RP6A, and 16RP8A			13	30		13	25	ns
f _{MAX} 16RP6A, 16RP6A, 16RP Maximum Frequency	16RP8A, 16RP6A, 16RP4A	Polarity Fuse Intact		20	40		28.5	40		NAI 1-
	Maximum Frequency	Polarity Fuse Blown		18.5	33		25	33		MHz

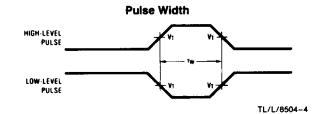
AC Test Load

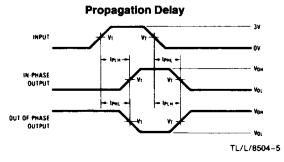


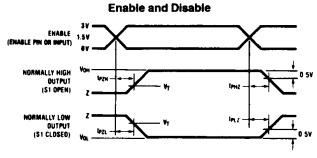
COM'L R1 = 390R1 = 200R2 = 750R2 = 390

Test Waveforms









TL/L/8504-6

Notes:

CL includes probe and jig capacitance.

In the example above, the phase relationships between inputs and outputs have been chosen arbitrarily.

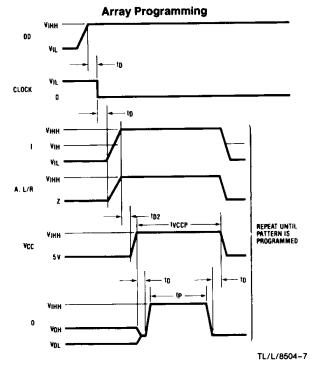
All input pulses are supplied by generators having the following characteristics: PRR = 1 MHz, $Z_{OUT} = 50\Omega$, $t_r \le 5$ ns, $t_t \le 5$ ns.

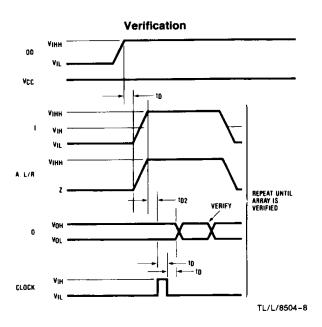
 t_{PD} is tested with switch S_{1} closed and $C_{L}\,=\,50$ pF.

For TRI-STATE outputs, output enable times are tested with $C_L = 50 \ pF$ to the 1.5V level; S_1 is open for high-impedance to HIGH tests and closed for high-impedance ance to LOW tests. Output disable times are tested with C_L = 5 pF. HIGH to high-impedance tests are made to an output voltage of V_{OH} -0.5V with S₁ open. LOW to high-impedance tests are made to the $V_{OL}\,+0.5V$ level with S_1 closed.

Symbol	Parame	eter	Min	Тур	Max	Units
VIHH	Program Level Input Voltage	11.5	11.75	12	٧	
		Output Program Pulse			50	
Інн I	Program Level Input Current	OD, L/R			50	mA
	_	All Other Inputs			15	
Іссн	Program Supply Current				900	_mA
tvccp	Pulse Width of V _{CC} @ V _{IHH}				60	μs
tp	Program Pulse Width		10	20	50	μs
t _D	Delay Time	100			ns	
t _{D2}	Delay Time after L/R Pin	10			μs	
	V _{CCP} Duty Cycle				20	%
Vp	Output Polarity and Security Fus	19.5	20	20.5	V	
l _{P1}	Security Fuse Programming Sup			400	mA	
I _{P2}	Output Polarity Programming Su	pply Current			200	mA
_· <u>.=</u>	Output Polarity and Security Fus	e Programming Pulse Width	10	40	70	μs
tpp	Output Polarity and Security Fus	e Programming Duty Cycle			50	%
	Rise Time of Output Programmir	ng and Address Pulses	11	1.5	10	V/µ
t _{RP}	Rise Time of Security Fuse Prog	ramming Pulses	1	1.5	10	,
V _{CCPP}	V _{CC} Value During Security Fuse	5.25	6	6.25	V	
	V _{CC} Value for First Verify	4.75	5	5.25		
	V _{CC} Value for High V _{CC} Verify	5.4	5.5	5.6		
	V _{CC} Value for Low V _{CC} Verify	4.4	4.5	4.6		
V _{CCOP}	V _{CC} Value During Output Polarit	y Programming	5.25	5.5	5.75	V

Programming Waveforms





Notes:

 V_{CC} (Low Voltage Verify) = 4.5V

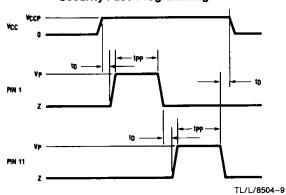
V_{CC} (High Voltage Verify) = 5.5V

 V_{CC} (First Verify) = 5V

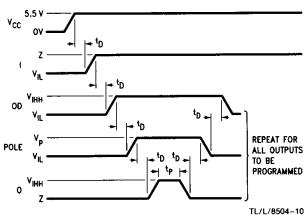
A Delay ($t_{\rm D2}$) must always precede the Positive Clock Transition. (e.g. see step 1.2.3.3 for underblow condition)

Programming Waveforms (Continued)

Security Fuse Programming



Output Polarity Programming



Programmer Development Systems

Vendor	PAL 20AP	PAL 20s (ALL)	PAL 24s (STD)	PAL 24s (FAST)		
Data I/O	—LogicPak	LogicPak (Rev-010) 1427 Card Set	—LogicPak (Rev-010)	LogicPak (Rev-010)		
Structured Design	—SD 1000	—SD 20/24 —SD1000	—SD 20/24 —SD1000	—SD 20/24 —SD1000		
STAG	—ZL 30	—PM202 (Rev 3) —PM2200	—PM202 (Rev 3) —PM2200	—PM202 (Rev 3) —PM2200		
DIGELEC		—UP803 (FAM51) or (FAM52)	—UP803 (FAM51) or (FAM52)	—UP803 (FAM51) or (FAM52)		
KONTRON		—MPP80S MOD 21				

Connection Diagrams

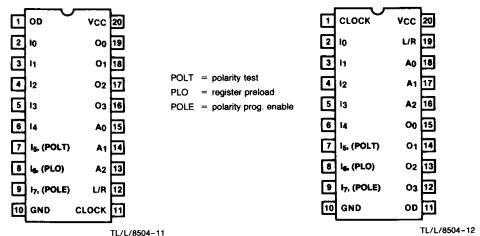


FIGURE 1. Pin Identification

Programming/Verifying Procedure*

Note: For programming purposes many PAL pins have double functions.

As long as Pin 1 is at V_{IHH} , Pin 11 is at ground, and Pin 12 is either at V_{IHH} or Z (as defined in Table I)—Pins 16, 17, 18, and 19 are outputs. The other pin functions are: I_0 (Pin 2) through I_7 (Pin 9) plus Pin 12 address the proper row: A0 (Pin 15), A1 (Pin 14), and A2 (Pin 13) address the proper product lines.

When Pin 11 is at V_{IHH} , Pin 1 is at ground, and Pin 19 is either at V_{IHH} or Z—Pins 12, 13, 14, and 15 are outputs. The other pin functions are: I_0 (Pin 2) through I_7 (Pin 9) plus Pin 19 address the proper row; A0 (now Pin 18), A1 (now Pin 17), and A2 (now Pin 16) address the proper product lines

*NSC programming spec. Rev. 1

Pre-Verification

Step 1.1 Pre-verification-Security-Fuses

Step 1.1.1 Raise Pin 2 to Vp.

Step 1.1.2 Place a 2k resistor to ground on Pin 1 and measure voltage across it.

-Reject part if measured voltage is less than 1.5V.

Step 1.1.3 Place a 2k resistor to ground on Pin 11 and measure voltage across it.

-Reject part if measured voltage is less than 1.5V.

Step 1.2 Pre-verification-Array

Step 1.2.1 Raise V_{CC} to 5.0V.

Step 1.2.2 Raise output disable, OD, to VIHH.

Step 1.2.3 Select an input line by specifying inputs and L/R as shown in Table I.

Step 1.2.4 Select a product line by specifying A0, A1, and A2 one-of-eight select as shown in Table II.

Step 1.2.5 Pulse the CLOCK pin and verify (with CLOCK at V_{IL}) that the output pin, O is TTL high.

—For TTL high, continue procedure.

-For TTL low, stop procedure and reject part.

Step 1.3 Pre-verification-Programmable Polarity Fuses (METHOD 1)

Step 1.3.1 Raise V_{CC} to 5.0V.

Step 1.3.2 Raise Pin 3 to Vp.

Step 1.3.3 Raise Pin 4 to Vp.

Step 1.3.4 Pulse the CLOCK pin and test (with CLOCK at V_{IL}) the state of the output pin, O.

—For unblown polarity fuse the output will be at logic 0.

—For blown polarity fuse the output will be at logic 1.

Step 1.4 Pre-verification—Programmable Polarity Fuses (METHOD 2)

Step 1.4.1 Raise V_{CC} to 5.0V.

Step 1.4.2 For any input condition determine the state of each output.

Step 1.4.3 Raise Pin 7 to V_P.

Step 1.4.4 Compare the output states now with their states at Step 1.4.2.

—If the state of the output has changed, then the output polarity fuse is unblown.

—If the state of the output is unchanged, then the output polarity fuse is blown

Step 1.5 Pre-verification—Programmable Polarity Fuses (METHOD 3)

Step 1.5.1 Raise V_{CC} to 5.0V.

Step 1.5.2 Raise all inputs to VIHH.

Step 1.5.3 Raise Pin 11 to VIHH.

Step 1.5.4 Pulse the CLOCK pin and verify (with CLOCK at V_{IL}) the state of the output pin.

—If output is at logic 0, then the output polarity fuse is unblown.

—If output is at logic 1, then the output polarity fuse is blown.

Programming Algorithm

Step 2.1 Raise Output Disable pin, OD, to VIHH.

Step 2.2 Programming pass. For all fuses to be blown:

Step 2.2.1 Lower CLOCK pin to ground.

Step 2.2.2 Select an input line by specifying inputs and L/R as shown in Table I.

Step 2.2.3 Select a product line by specifying A0, A1, and A2 one-of-eight select as shown in Table II.

Step 2.2.4 Raise V_{CC} to V_{IHH}.

Step 2.2.5 Program the fuse by pulsing the output pins of the selected product group one at a time to V_{IHH} (as shown in the Programming Waveforms).

Step 2.2.6 Lower V_{CC} to 5V.

Step 2.2.7 Repeat this procedure from Step 2.2.2 until pattern is complete.

Step 2.3 First verification pass. For all fuse locations:

Step 2.3.1 Select an input line by specifying inputs and L/R as shown in Table I.

Step 2.3.2 Select a product line by specifying A0, A1, and A2 one-of-eight select as shown in Table II.

Step 2.3.3 Pulse the CLOCK pin and verify (with CLOCK at V_{II}) that the output pin, O, is in the correct state.

—For verified output state, continue procedure.

-For overblow condition, stop procedure and reject part.

—For underblow condition, reexecute steps 2.2.4 through 2.2.6 and 2.2.3. If successful, continue procedure. After three attempts to blow fuse without success, reject part.

Step 2.3.4 Repeat this procedure from step 2.3.1 until the entire array is exercised.

Programming Algorithm (Continued)

Step 2.4 High Voltage Verify. For all fuse locations:

Step 2.4.1 Raise V_{CC} to 5.5V.

Step 2.4.2 Select an input line by specifying inputs and L/R as shown in Table I.

Step 2.4.3 Select a product line by specifying A0, A1, and A2 one-of-eight select as shown in Table II.

Step 2.4.4 Pulse the CLOCK pin and verify (with CLOCK at $V_{\parallel L}$) that the output pin, 0, is in the correct state.

—For verified output state, continue procedure.

-For invalid output state, stop procedure and reject part.

Step 2.4.5 Repeat this procedure from step 2.4.2 until the entire array is exercised.

Step 2.5 Low Voltage Verify. For all fuse locations:

Step 2.5.1 Lower V_{CC} to 4.5V.

Step 2.5.2 Select an input line by specifying inputs and L/R as shown in Table I.

Step 2.5.3 Select a product line by specifying A0, A1, and A2 one-of-eight select as shown in Table II.

Voltage Legend

L = Low level input voltage, V_{IL} H = High level input voltage, V_{IH}

TABLE I. Input Line Select

Input Line	Pin Identification										
Number	17	l ₆	l ₅	14	l ₃	l ₂	11	l ₀	L/R		
0	нн	НН	HH	HH	HH	НН	НН	L	Ζ		
1	НН	HH	HH	HH	HH	HH	HH	Н	Z		
2	HH	HH	HH	HH	HH	HH	HH	L	HH		
3	HH	HH	HH	HH	HH	HH	HH	Н	HH		
4	НН	HH	HH	HH	HH	HH	L	HH	Z		
5	HH	HH	HH	HH	HH	HH	Н	НН	Ζ		
6	НН	HH	HH	HH	HH	HH	L	HH	HH		
7	HH	HH	HH	HH	HH	HH	Н	HH	HH		
8	НН	HH	HH	HH	HH	L	HH	HH	Ζ		
9	HH	HH	HH	HH	HH	Н	HH	HH	Z		
10	HH	HH	HH	HH	HH	L	HH	НН	HH		
11	HH	HH	HH	HH	НН	Н	НН	HH	HH		
12	HH	HH	HH	HH	L	HH	HH	HH	Z		
13	HH	HH	HH	HH	Н	HH	HH	НН	Z		
14	HH	HH	HH	HH	L	HH	HH	НН	HH		
15	HH	HH	HH	HH	Н	HH	НН	HH	HH		
16	HH	HH	HH	L	HH	HH	HH	HH	Z		
17	HH	HH	HH	Н	HH	HH	HH	HH	Z		
18	HH	HH	HH	L	HH	НН	HH	НН	HH		
19	HH	HH	HH	Н	HH	HH	HH	HH	HH		
20	HH	HH	L	HH	HH	HH	HH	HH	Z		
21	НН	HH	Н	HH	HH	HH	HH	HH	Ζ		
22	HH	HH	L	HH	HH	HH	HH	HH	HH		
23	HH	HH	Н	HH	HH	HH	HH	HH	HH		
24	HH	L	HH	HH	HH	HH	НН	HH	Z		
25	HH	Н	HH	HH	HH	HH	HH	HH	Ζ		
26	HH	Ļ	HH	HH	HH	HH	HH	HH	HH		
27	HH	Н	HH	HH	HH	HH	HH	ΗН	HH		
28	L	HH	HH	HH	HH	HH	HH	HH	Z		
29	Н	HH	HH	HH	HH	HH	HH	НН	Z		
30	L	HH	HH	HH	HH	НН	HH	HH	HH		
31	H	HH	HH	HH	HH	HH	HH	HH	HH		

Step 2.5.4 Pulse the CLOCK pin and verify (with CLOCK at V_{\parallel}) that the output pin, O, is in the correct state.

--For verified output state, continue procedure.

—For invalid output state, continue procedure and reject part.

Step 2.5.5 Repeat this procedure from 2.5.2 until entire array is exercised.

Programming the Security Fuses

Step 3.1 Verify per Step 2.4 and Step 2.5.

Step 3.2 Raise V_{CC} to 6V.

Step 3.3 Program the first fuse by pulsing Pin 1 to V_P. (From 1 to 5 pulses is acceptable.)

Step 3.4 Program the second fuse by pulsing Pin 11 to V_P. (1 to 5 pulses is acceptable.)

Step 3.5 Verify per Step 1.1: — A device is "secured" if it verifies as blank per step 1.1.

HH = High level program voltage, V_{1HH} Z = 10 k Ω to 5V

TABLE II. Input Line Select

Product Line			Pin Id	entific	ation		
Number	03	02	01	00	A ₂	A ₁	A ₀
0, 32	Z	Z	Z Z Z Z Z Z Z Z	HH	Z	Z Z	z
1,33	Ζ	Z	Z	HH	Z	Z	HH
2, 34	Z	Z	Z	HH	Z	НН	Z
3, 35	Z	Z	Z	HH	Z	HH	HH
4, 36	Z	Z	Z	HH	HH	Z Z	Z
5, 37	Z	Z	Z	HH	HH		HH
6, 38	Z	Z	Z	HH	HH	HH	Z
7, 39	Z	Z	Z	HH	HH	НН	HH
8, 40	Z	Z	HH	Z		Z Z	Z
9, 41	Z	Z	HH	Z	Z	Z	HH
10, 42	Z	Z	HH	Z	Z Z Z Z	HH	Z
11, 43	Ζ	Z	HH	Z		HH	нн
12, 44	Z	Z	HH	Z	HH	Z Z	Z
13, 45	Z	Z	HH	Z	HH	Z	HH
14, 46	777777777777777777777777777777777777777	Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z	HH	Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z	HH	HH	Z
15, 47	Z	Z	HH	Z	HH	HH	HH
16, 48	Z	HH	Z	Z	Z Z Z Z	Z Z	z
17, 49	Z	HH	Z	Z	Z	Z	HH
18, 50	Z	HH	Z	Z	Z	НН	Z
19, 51	Z	HH	Z	Z	Z	НН	HH
20, 52	Z	HH	Z	Z	HH	Z Z	Z
21, 53	Z	HH	Z	Z	HH	Z	нн
22, 54	Z	HH	Z	Z	HH	HH	Z
23, 55	Z	HH	Z	Z	HH	HH	нн
24, 56	HH	Ζ	Z	Z	Z	Z Z	Z
25, 57	НН	Z Z	Z	Z	Z Z Z Z	Z	HH
26, 58	HH	Z	Z	Z	Z	HH	Z
27, 59	HH	Z Z	HH Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z	Z Z Z Z Z Z Z Z		HH	HH
28, 60	HH	Z Z	Z	Z	HH	Z Z	Z
29, 61	HH	Z	Z	Z	HH	Z	HH
30, 62	HH	Z Z	Z	Z	Н	нн	Z
31, 63	НН	Z	Z	Z	HH	HH	HH

Programming the Output Polarity Fuses

Initial Programming Pass.

Step 4.1 Raise V_{CC} to 5.5V.

Step 4.2 Set all inputs and output pins to Z.

Step 4.3 Raise output disable, OD, to V_{IHH} to disable the selected outputs.

Step 4.4 Raise Polarity Enable, Pin 9 (POLE) to Vp.

Step 4.5 Program the fuse by pulsing the desired output to V_{IHH} .

Step 4.6 Lower Pin 9 (POLE) to VIH.

Step 4.7 Lower OD to Vil.

Step 4.8 Repeat this procedure from Step 4.3 to Step 4.7 until all desired outputs are programmed.

Output Register PRELOAD

The PRELOAD function allows the register to be loaded from data placed on the output pins. This feature aids functional testing which would otherwise require a state sequencer for test coverage. The procedure for PRELOAD

is as follows:

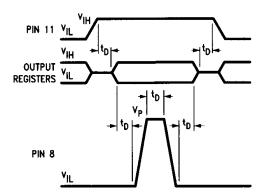
- 1 Raise V_{CC} to 4.5V.
- 2 Disable output registers by setting Pin 11 to VIH.
- 3 Apply V_{IL}/V_{IH} to all output registers.
- 4 Pulse Pin 8 to Vp. Then back to 0 V.
- 5 Remove VIL/VIH from all output registers.
- 6 Lower Pin 11 to V_{IL} to enable the output registers.
- 7 Verify for V_{OL}/V_{OH} at all output registers.

National Mask Logic (NML)

If a large number of PALs of the same pattern are to be used, it may be economical to consider mask-programming the PAL to avoid programming costs. These mask-programmed devices will meet or exceed all of the performance specifications of the fuse-programmed devices they replace. These specifications are listed previously in this data sheet

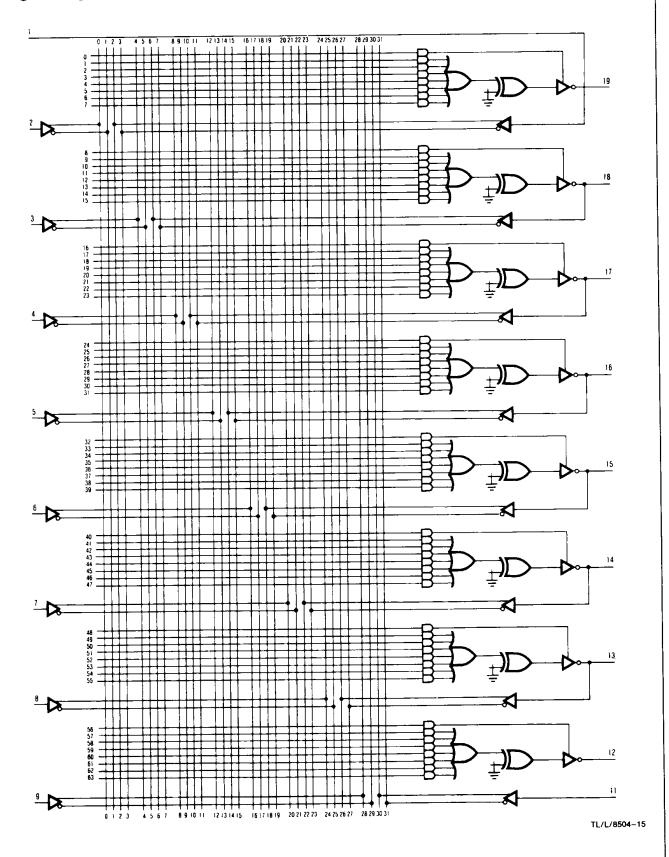
To generate a NML PAL, National requires a set of logic equations written in PALASMTM format, plus test vectors which the user generates as acceptance criteria for the finished product.

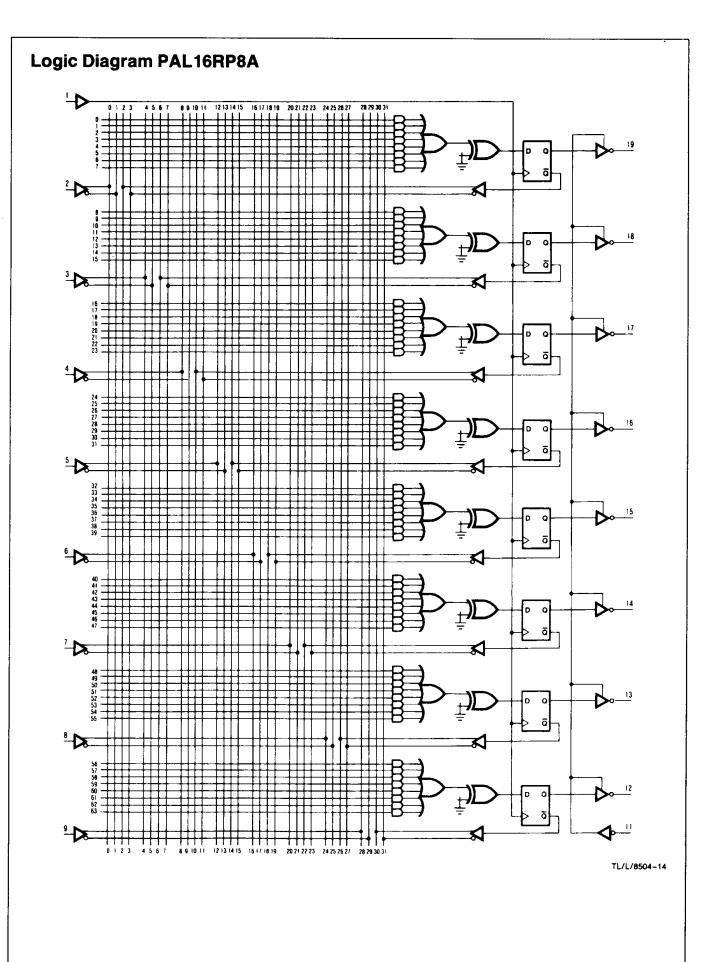
Programming Waveform



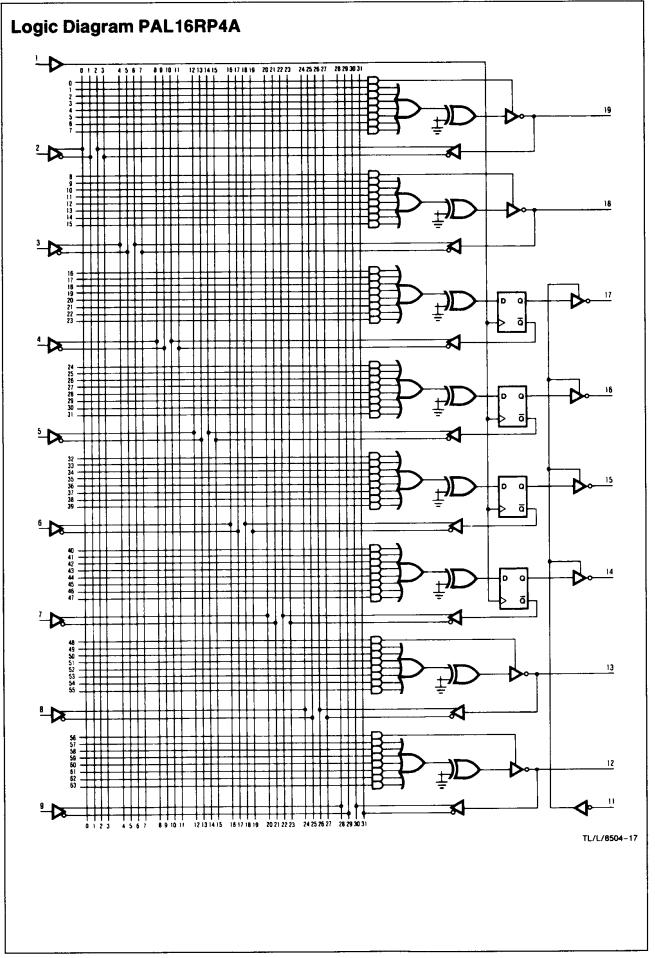
TL/L/8504-13

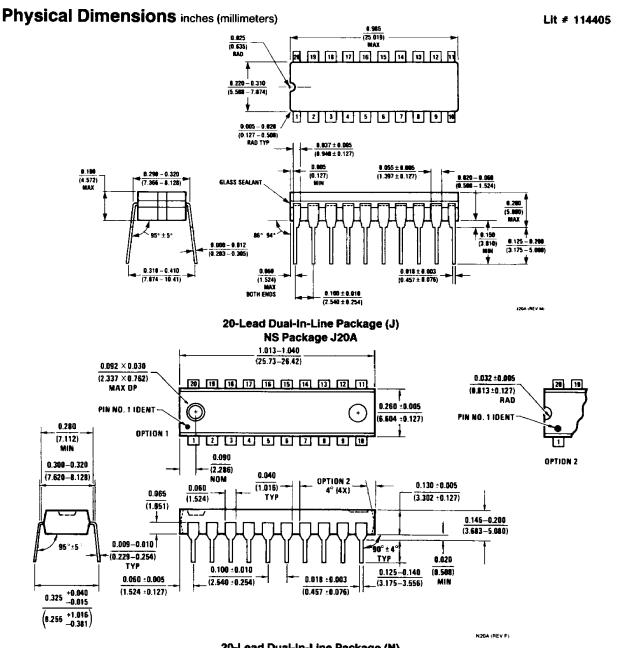
Logic Diagram PAL16P8A





Logic Diagram PAL16RP6A 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 19 ā 하 ā <u>6</u> ō ¹-**D** <u>-</u>De-12 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 TL/L/8504-16





20-Lead Dual-In-Line Package (N) NS Package N20A

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- A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.



National Semiconductor Corporation 2900 Semiconductor Drive P.O. Box 58090 Santa Clara, CA 95052-8090 Tel: (408) 721-5000 TWX: (910) 339-9240

National Semiconducto GmbH Westendstrasse 193-195

Westendstrasse 193-195 D-8000 Munchen 21 West Germany Tel: (069) 5 70 95 01 Telex: 522772 NS Japan Ltd. 4-403 lkebukuro, Toshima-ku, Tokyo 171, Japan Tel: (03) 988-2131 FAX: 011-81-3-988-1700 National Semiconductor Hong Kong Ltd. Southeast Asia Marketing Austin Tower, 4th Floor 22-26A Austin Avenue Tsimshatsu, Kowloon, H.K. Tel: 3-7231290, 3-7243645 Cable: NSSEAMKTG Telex: 52996 NSSEA HX

National Semicondutores Do Brasil Ltda. Av. Brig. Faria Lima, 830 8 Andar 01452 Sao Paulo, SP. Brasil Tel: (55/11) 212-5066 Telex: 391-1131931 NSBR BR National Semiconductor (Australia) PTY, Ltd. 21/3 High Street Bayswater, Victoria 3153 Australia Tel: (03) 729-6333 Telex: AA32096